
Wiper control for Intermittent and Wipe/ Wash Mode

Description

The U 842 B circuit is designed as an interval and wipe/ wash timer for automotive wiper control.

The interval pause can be set in a range from 3 s to 11 s by an external 1-k Ω potentiometer. Wipe/wash mode has priority over the interval mode.

U 842 B controls the wiper motor with/without park switch signal.

The integrated relay driver is protected against short circuit and is switched to conductive condition in the case of a load dump. With only a few external components protection against RF interference and transients (ISO/TR 7637-1/3) can be achieved.

Features

- Interval input: low side
- Wipe/ wash input: low side
- Park input: high side (park position)
- Output driver protected against short circuit
- All time periods determined by RC oscillator
- Fixed relay activation time of 500 ms
- Adjustable interval pause from 3 s to 11 s
- Fixed pre-wash delay of 400 ms
- Dry wiping
 - With park switch signal: 3 cycles
 - Without park switch signal: 2.8 s
- Inputs INT, WASH and PARK digitally debounced
- All inputs with integrated RF protection
- Load dump protection and interference protection according to ISO 7637-1/3 (DIN 40839)

Application

Digital/ wipe-wash control for rear or front wiper

Block Diagram

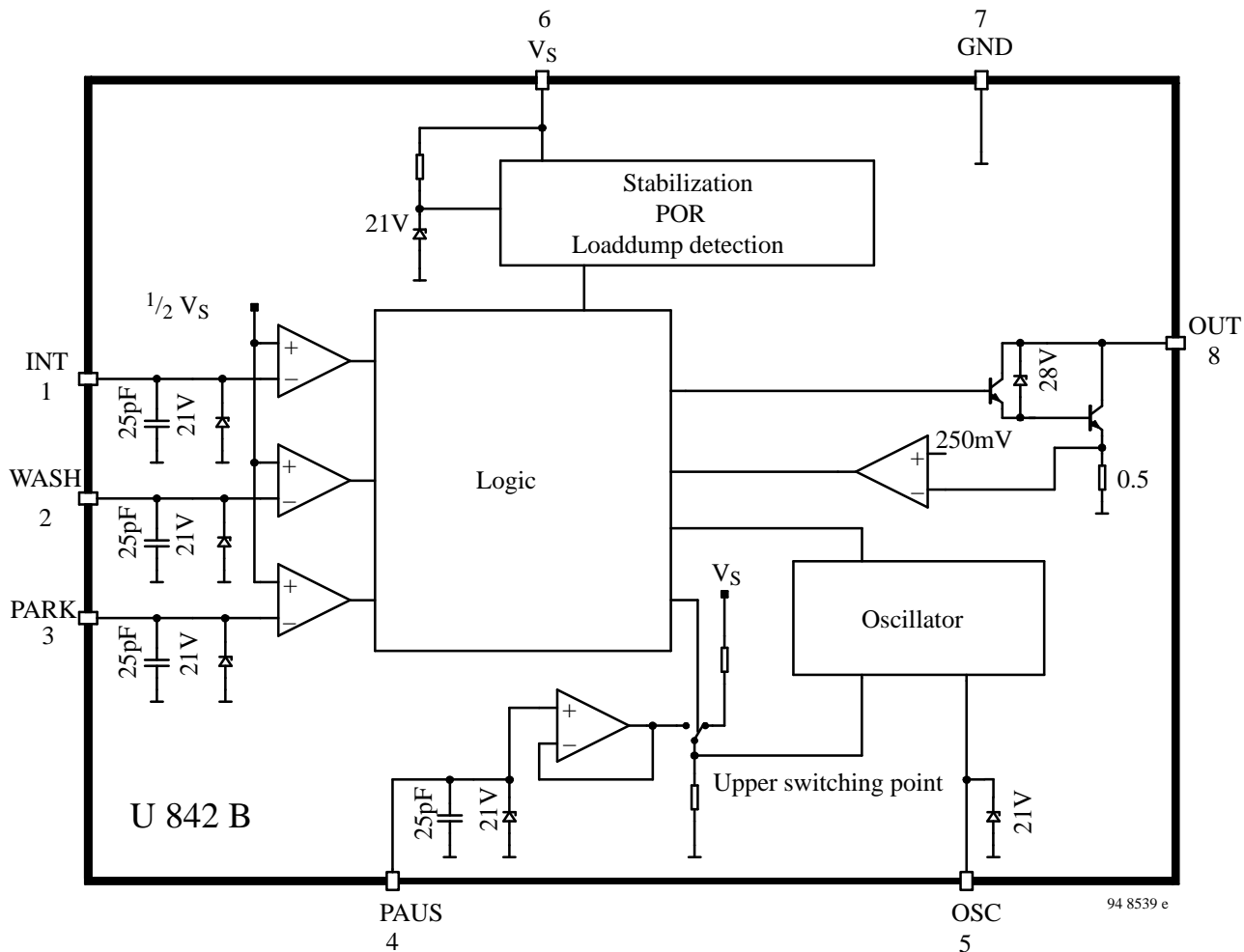


Figure 1 Block diagram

Pin Description

| Pin | Symbol | Function |
|-----|--------|-------------------|
| 1 | INT | Interval input |
| 2 | WASH | Wipe/ wash input |
| 3 | PARK | Park switch input |
| 4 | PAUS | Pause time adjust |

| Pin | Symbol | Function |
|-----|----------------|------------------|
| 5 | OSC | Oscillator input |
| 6 | V _S | Supply voltage |
| 7 | GND | Ground |
| 8 | OUT | Relay output |

Basic circuit

Power supply

For reasons of interference protection and surge immunity, an RC circuitry has to be provided to limit the current and to supply the integrated circuit in the case of supply voltage drops.

Suggested values: $R_1 = 180 \Omega$, $C_1 = 47 \mu\text{F}$,
(see figure 2)

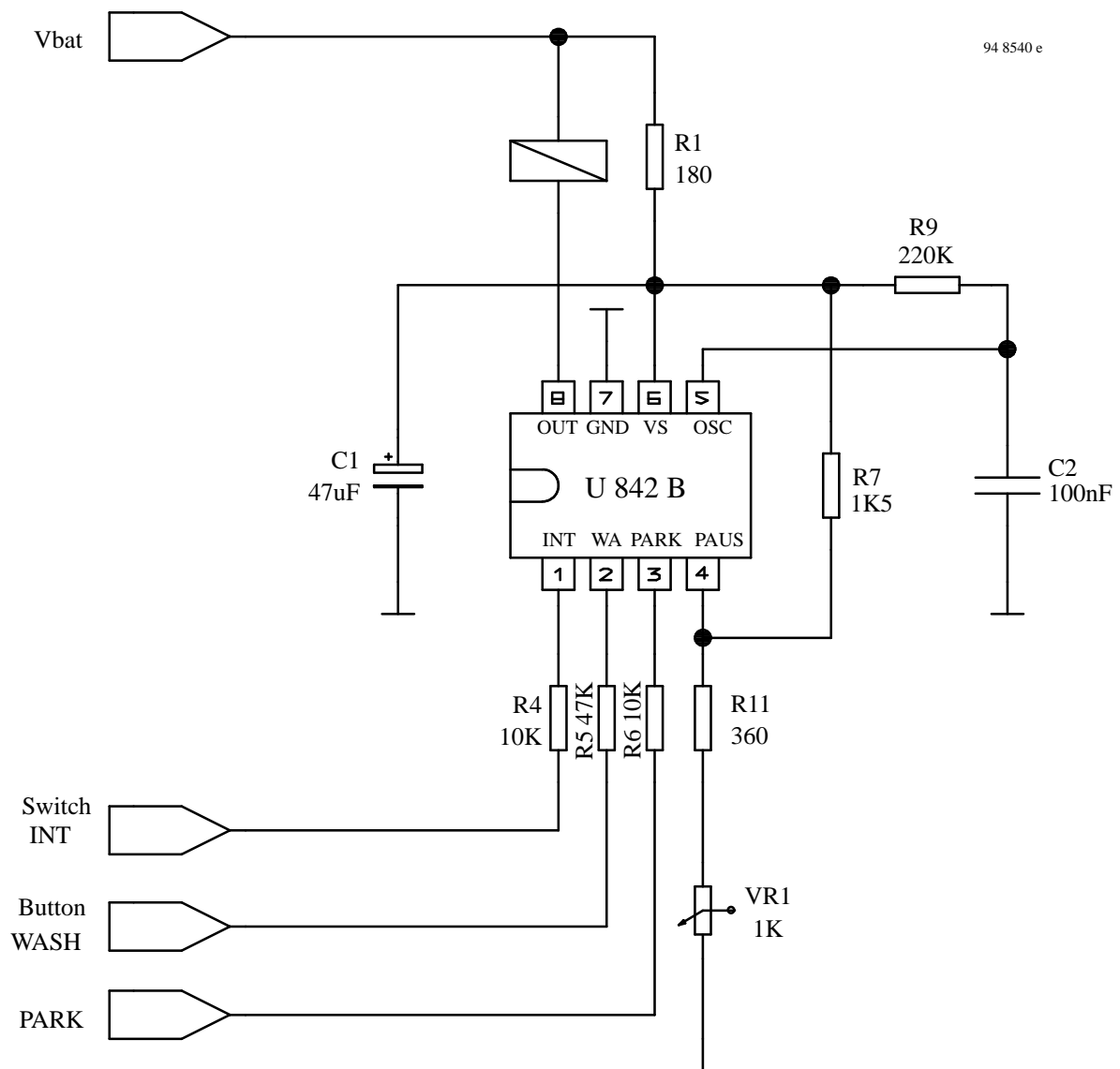


Figure 2 Basic circuitry

The supply (Pin 6) is clamped with a 21-V Zener diode. The operation voltage ranges between $V_{bat} = 9\text{ V}$ to 16 V .

The capacitor, C_1 , can be dimensioned smaller (typically: $10\text{ }\mu\text{F}$) if a diode is used in the supply against polarity reversal. In this case of negative interference pulses there is only a small discharge current of the circuit.

Oscillator

All timing sequences in the circuit are derived from an RC oscillator which is charged by an external resistor, R_9 , and discharged by an integrated $2\text{-k}\text{ }\Omega$ resistor. The basic

frequency, f_0 , is determined by the capacitor, C_2 , and an integrated voltage divider. The basic frequency is adjusted to 320 Hz (3.125 ms) by $C_2 = 100\text{ nF}$ and $R_9 = 220\text{ k}\Omega$.

The tolerances and the temperature coefficients of the external components determine the precision of the oscillator frequency. A 1% metallic-film resistor and a 5% capacitor are recommended..

The debouncing times of the inputs, the turn-on time of the relay (t_5), the pre-wash delay (t_1), the dry wiping time (t_2) and the debouncing time (t_7 , short circuit detection) depend on the oscillator frequency (f_0) as follows:

Timing

Table 1

| | |
|-----------------------|---------------------------------|
| Fixed: | |
| Relay activation time | $t_5 = 160 * 1/f_0$ |
| Dry wiping | $t_2 = 896 * 1/f_0$ or 3 cycles |
| Interval pause | $t_6 = 872 * 1/f_{INT}$ |
| Switch on delay INT | $t_{4D} = 8 * 1/f_0$ |
| Variable: | |
| Debouncing time INT | $t_4 = 24$ to $32 * 1/f_0$ |
| Debouncing time WASH | |
| 1. pre-wash delay | $t_1 = 112$ to $128 * 1/f_0$ |
| 2. reverse debouncing | $t_{1,R} = 16$ to $32 * 1/f_0$ |
| Debouncing time PARK | $t_8 = 6$ to $8 * 1/f_0$ |
| Debouncing time SC | $t_7 = 2$ to $3 * 1/f_0$ |

Variable debouncing times

Debouncing is basically done by counting of oscillator clocks starting with the occurrence of any input signal.

Caused by the asynchronism of input signal and IC-clock the debouncing time may vary in a certain range.

Figure 3 shows the short circuit debouncing as an example: During the relay activation a comparator monitors the output current at each positive edge of the clock to load a 3 stage shift register in the case of a detected short circuit condition i.e. $I > 500$ mA. With the third edge the output stage is disabled. Dependent on the short circuit occurrence the delay time may range from 2 to 3 clock cycles.

The timing can be adjusted by variation of the external frequency-determining components (R/C).

The potentiometer at Pin 4 determines the interval pause, which can be varied by adjusting the upper charging threshold of the oscillator. For all other time periods, an internal voltage divider determines the upper charging threshold of the oscillator (see figure 1).

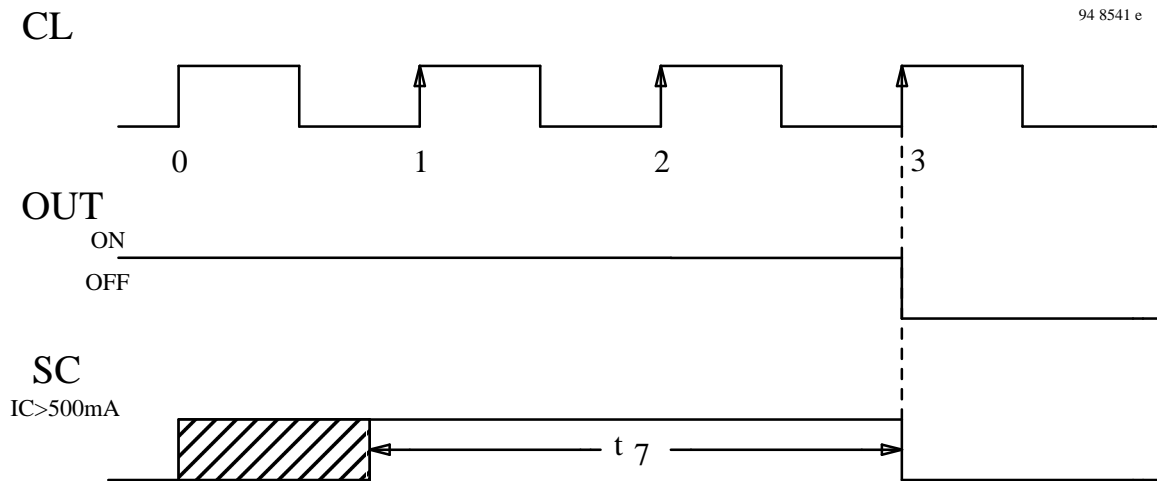


Figure 3 The debouncing of the short circuit detection

Relay output

The relay output is an open collector Darlington transistor with an integrated 28-V Z-diode for limitation of the inductive cut-out pulse of the relay coil. The maximum static collector current must not exceed 300 mA and the saturation voltage is typically 1.2 V for a current of 200 mA.

The collector current is permanently measured by an integrated shunt, and in the case of a short circuit ($I_C > 500$ mA) to V_{bat} , the relay output is stored disabled.

The short circuit buffer is reset by opening the INT and

WASH switches. As long as the short condition exists a further activation of these switches will disable the output stage again. Otherwise the normal wipe operation is performed.

In order to avoid short term disabling caused by current pulses of transients a 10 ms debounce period (t_7) is provided (see figure 3).

During a load dump pulse, the output transistor is switched to conductive condition to prevent destruction. The short circuit detection is suppressed during the load dump.

Interference voltages and load dump

The IC supply is protected by R_1 , C_1 and an integrated 21-V Z-diode. The inputs are protected by a series resistor, integrated 21-V Z-diode and RF capacitor.

The RC-configuration stabilizes the supply of the circuit during negative interference voltages to avoid power on reset (POR).

The relay output is protected against short interference peaks by an integrated 28-V Z-diode. During load dump, the relay output is switched to conductive condition if the battery voltage exceeds approximately 30 V. The output transistor is dimensioned so that it can absorb the current produced by the load dump pulse.

Power-On-Reset

When the operating voltage is switched on, an internal power-on-reset pulse (POR) is generated which sets the logic of the circuits to defined initial condition. The relay output is disabled, the short circuit buffer is reset.

Functional description

Interval function

The circuit is brought to its interval mode with the input

switch INT operated for more than 625 ms ($t > t_4 + t_{4D} + t_5$).

This time includes:

- 100 ms debounce time t_4
- 25 ms INT switch on delay t_{4D}
- 500 ms relay activation time t_5

If the INT input is toggled for $125 \text{ ms} < t < 625 \text{ ms}$ the relay activation time t_5 lapses anyway and the wiper performs one turn. For correct interval function the INT input has to be activated afterwards as described.

The beginning of the interval pause depend upon the application with or without wiper motor park switch (see figures 4, 5, 6 and 7).

Interval function with park switch feedback

During the relay activation time the wiper motor leaves its park position and the park switch changes its potential from V_{Bat} to GND. After the relay is switched off the wiper motor is supplied via the park switch until the park position is reached again. The park switch changes its potential from GND back to V_{Bat} . With the park switch connected to the park input (Pin 3) the interval pause t_6 starts after the 25 ms debounce time (t_7) is over (see figures 4 and 5).

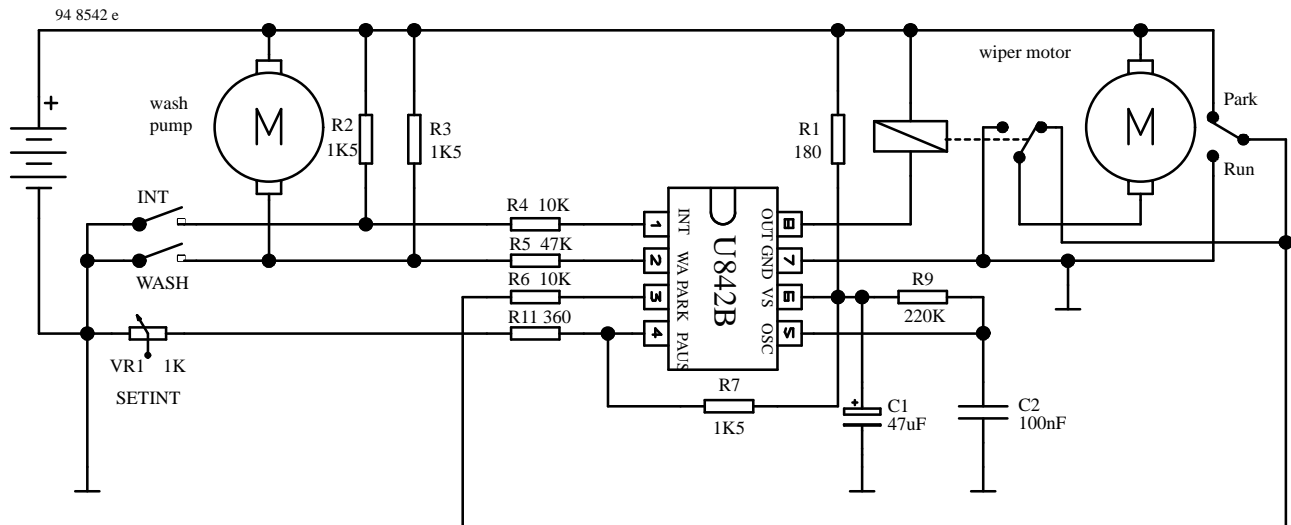


Figure 4 Application circuit with park switch feedback

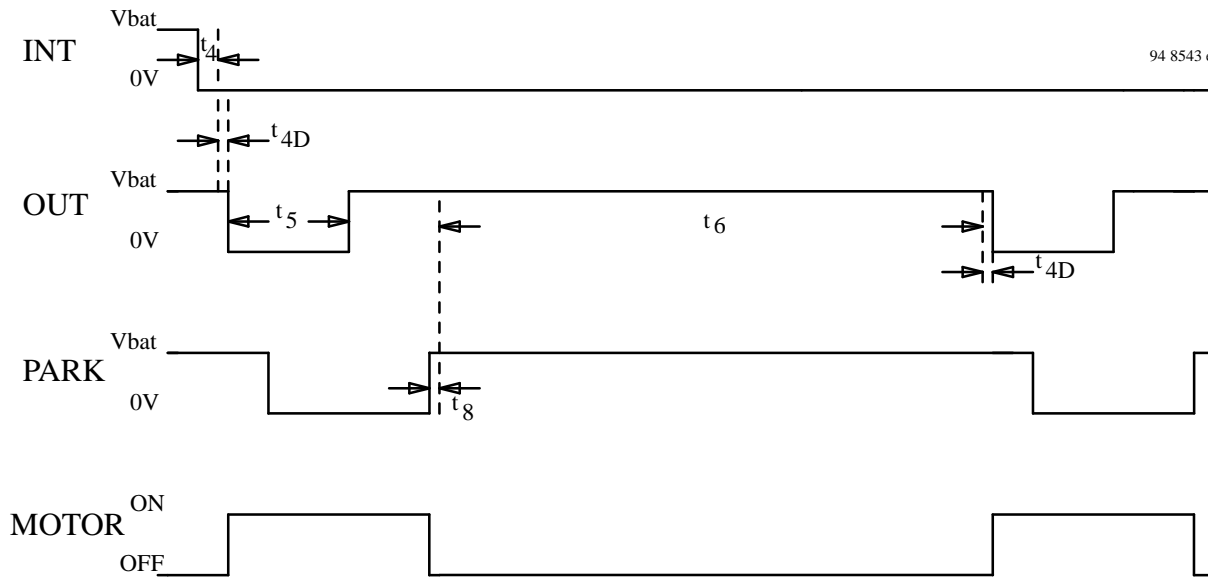


Figure 5 Intermittent circuit function with park position feedback

Interval function without park switch feedback

If the park input of the circuit is not connected with the park switch of the wiper motor (see figure 6), the interval pause starts directly after the turn-on time of the relay is over (see figure 7).

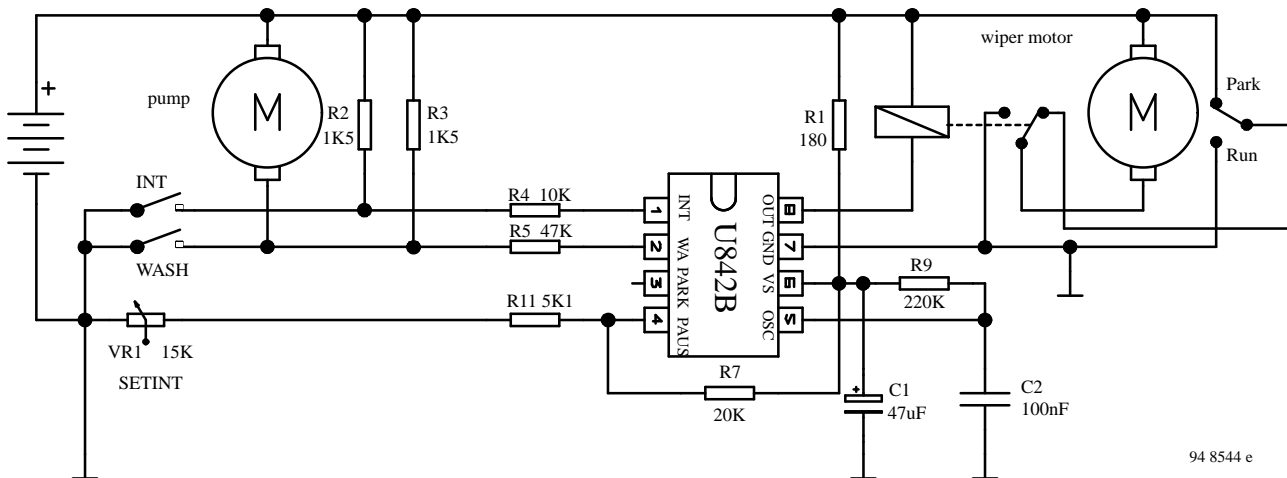


Figure 6 Application circuit without park position feedback

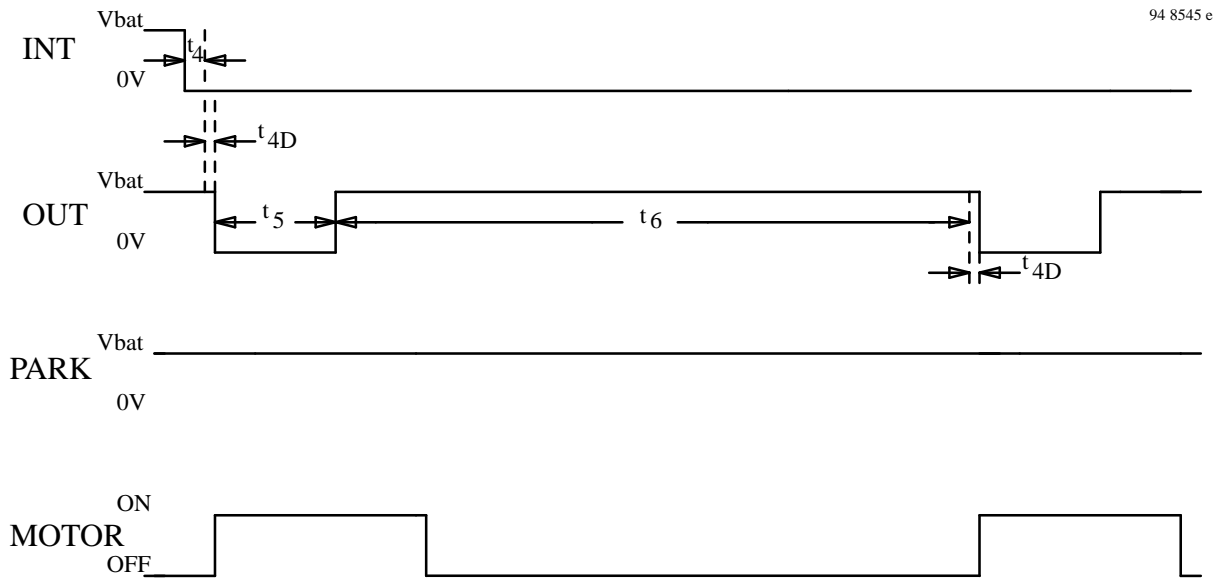


Figure 7 Intermittent circuit function without park position feedback

Wipe/ wash operation

After operating the WASH switch, the relay is activated after the debounce time, t_1 . As long as the switch is pushed, water is sprayed on the windscreen by the wash pump. When it is released, the dry wiping starts after 100 ms reverse debouncing (t_{1R}).

Wipe/ wash mode with park position feedback

If the park input of the circuit is connected to the park switch, the dry wiping lasts three full wipe cycles (see figure 8).

During the third cycle, the wiper motor is supplied via the park switch because the relay driver is switched off after the second cycle.

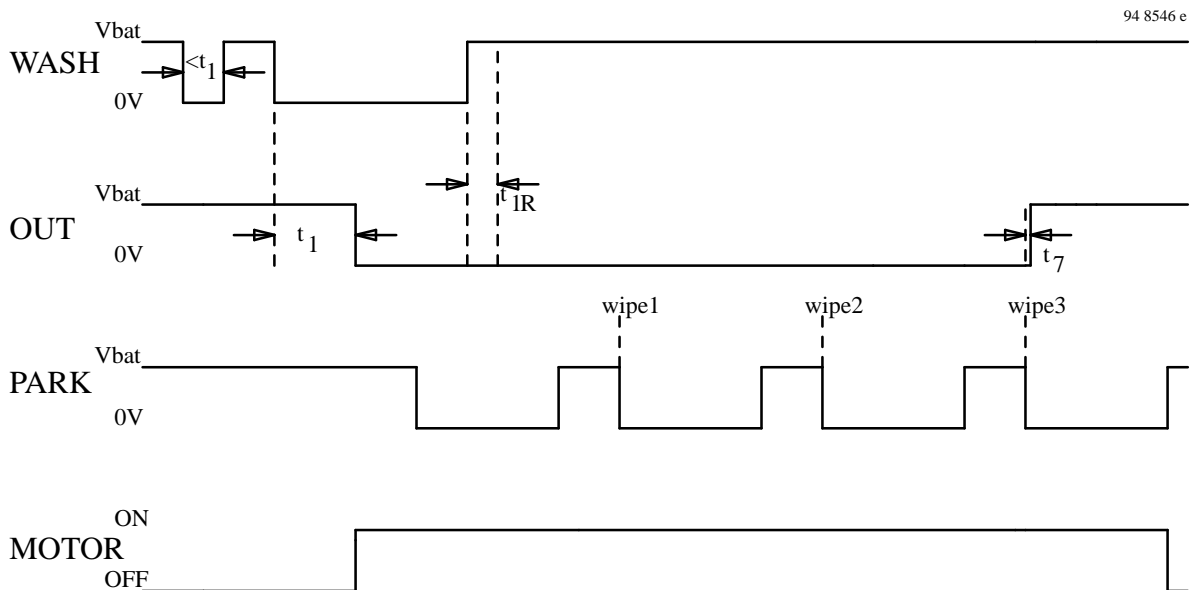


Figure 8 Wash operation with park switch signal

Wipe/ wash mode without park position feedback

If U 842 B is used without the wiper motor's park switch resistor. Therefore the driver stage switches off after the Pin 3 stays at high potential via its integrated pull up fixed dry wiping time t_2 .

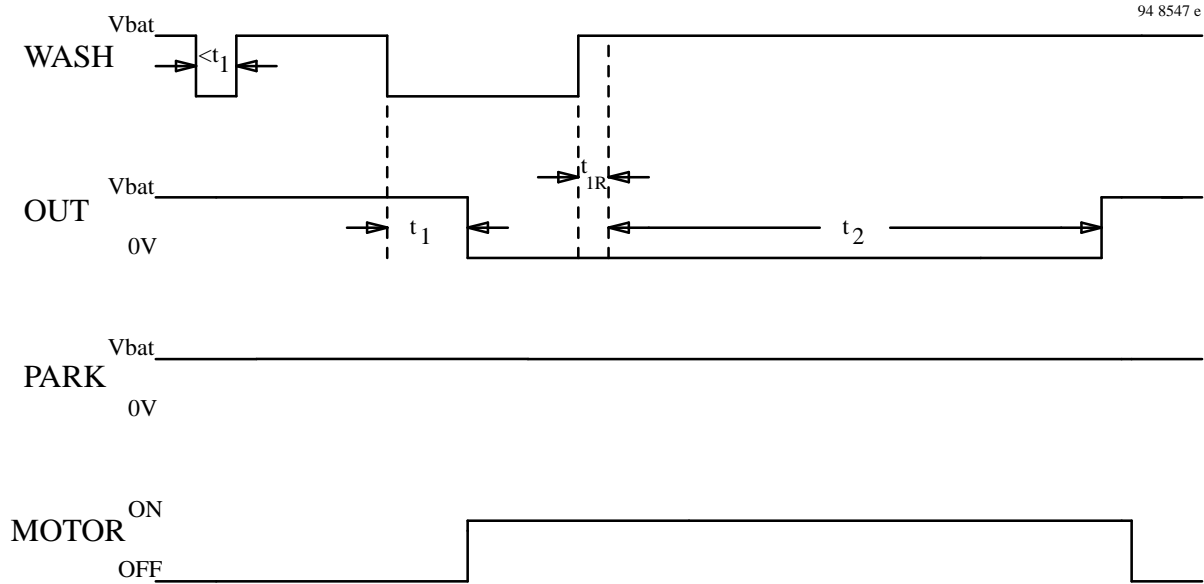


Figure 9 Wash operation without park signal report

Wipe/ wash mode priority

The wipe/wash mode has priority over the interval mode – therefore the interval function is interrupted as soon as the WASH switch is operated longer than the debounce time t_1 . With or without park switch feedback, after relay

activation time is over (no park switch feedback) or after the third wipe (park switch feedback), the interval mode is continued with an interval pause t_6 (see figures 10 and 11).

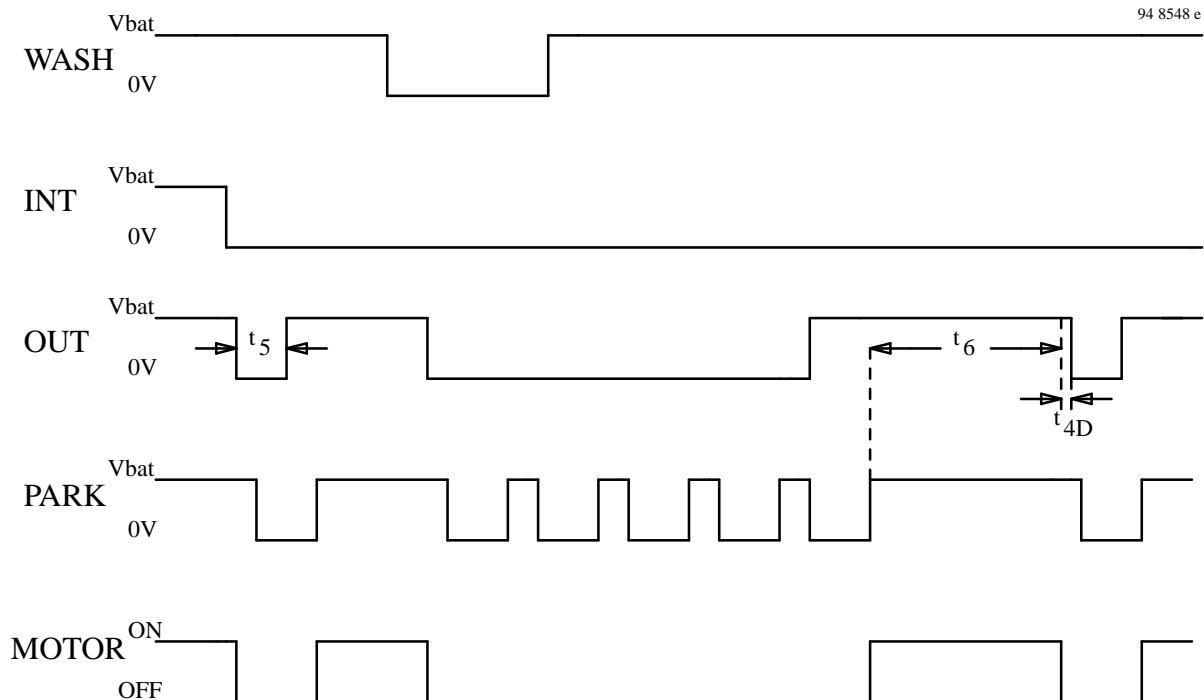


Figure 10 Wipe/ wash priority with park position feedback

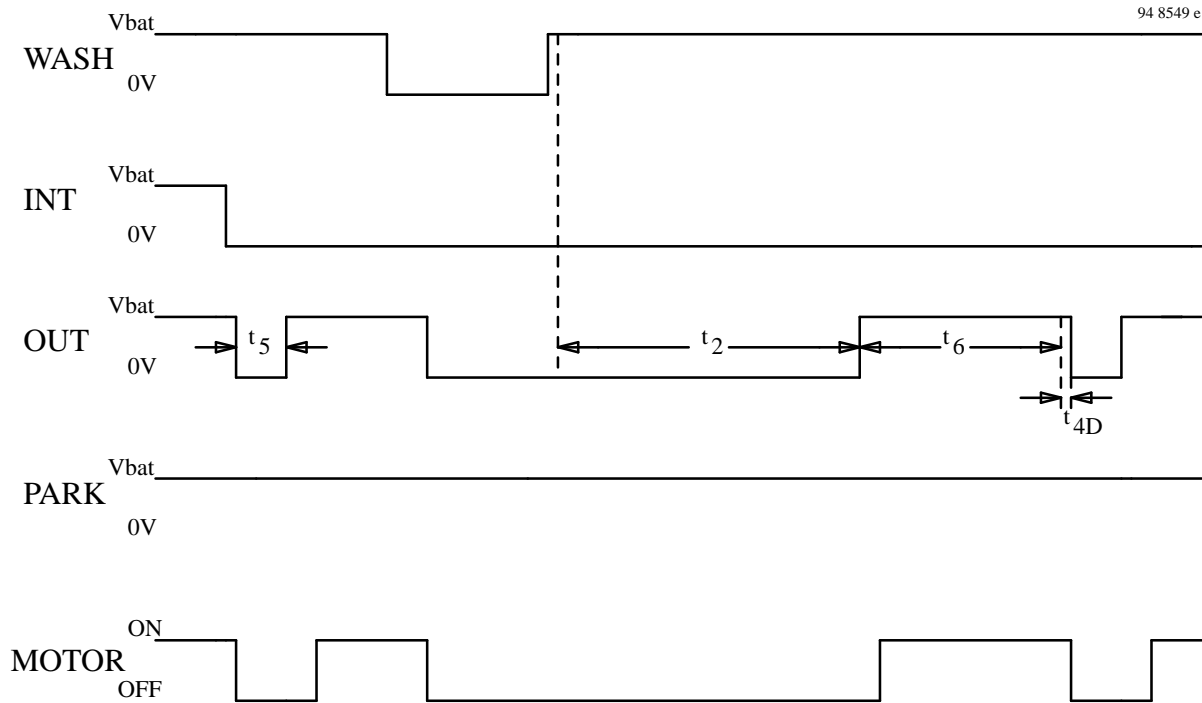


Figure 11 Wash/ wipe priority without park position feedback

Absolute Maximum Ratings

| Parameters | Symbol | Value | Unit |
|------------------------------|-----------|-------------|------|
| Supply voltage | V_{bat} | 24 | V |
| $t = 60\text{ s}$ | V_{bat} | 18 | V |
| $t = 600\text{ s}$ | | | |
| Ambient temperature range | T_{amb} | -30 to +100 | °C |
| Storage temperature range | T_{stg} | -40 to +100 | °C |
| Maximum junction temperature | T_j | 150 | °C |

Thermal Resistance

| Parameters | Symbol | Maximum | Unit |
|--------------------|------------|---------|------|
| Thermal resistance | R_{thja} | 110 | K/W |
| DIP 8 | R_{thja} | 160 | K/W |
| SO 8 | | | |

Electrical Characteristics

$V_{\text{bat}} = 13.5 \text{ V}$, $T_{\text{amb}} = 25^\circ\text{C}$, reference point ground (Pin 7), circuit with recommended external circuitry (see figure 2)

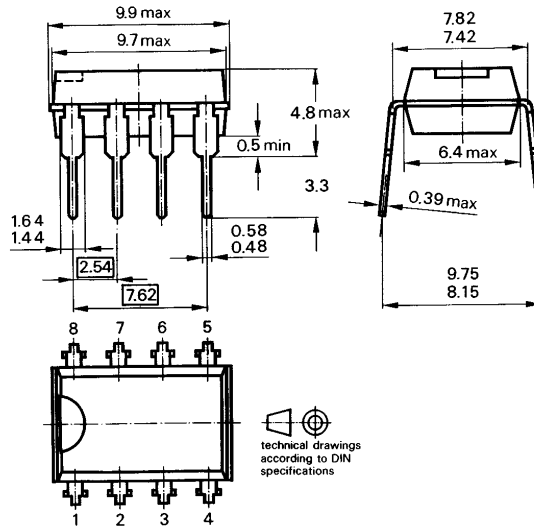
| Parameters | Test Conditions / Pin | Symbol | Min | Typ | Max | Unit |
|----------------------------|-----------------------|------------------|-----|-----------|-----|---------------|
| Supply | | | | | | |
| Supply voltage range | | V_{bat} | 9 | | 16 | V |
| Supply current | | I_6 | | | 3 | mA |
| Undervoltage threshold POR | | V_6 | | 3.5 | | V |
| Series resistance | | R_1 | | 180 | | Ω |
| Filter capacitance | | C_1 | | 47 | | μF |
| Internal Z-diode | | V_6 | | 21 | | V |
| INT input Pin 1 | | | | | | |
| Protective diode | | V_1 | | 21 | | V |
| Internal capacitance | | C_1 | | 25 | | pF |
| Threshold | | V_1 | | $0.5 V_6$ | | Ω |
| Pull-up resistance | | R_1 | | 20 | | k Ω |
| External series resistance | | R_S | | 10 | | k Ω |
| PARK input Pin 3 | | | | | | |
| Protective diode | | V_3 | | 21 | | V |
| Internal capacitance | | C_3 | | 25 | | pF |
| Threshold | | V_3 | | $0.5 V_6$ | | Ω |
| Pull-up resistance | | R_3 | | 20 | | k Ω |
| External series resistance | | R_S | | 10 | | k Ω |
| WASH input Pin 2 | | | | | | |
| Protective diode | | V_2 | | 21 | | V |
| Internal capacitance | | C_2 | | 25 | | pF |
| Threshold | | V_2 | | $0.5 V_6$ | | Ω |
| Pull-up resistance | | R_2 | | 100 | | k Ω |
| External series resistance | | R_S | | 47 | | k Ω |
| PAUS input Pin 4 | | | | | | |
| Protective diode | | V_4 | | 21 | | V |
| Internal capacitance | | C_4 | | 25 | | pF |
| Relay output Pin 8 | | | | | | |
| Saturation voltage 100 mA | | V_8 | | 1.0 | | V |
| Saturation voltage 200 mA | | V_8 | | 1.2 | | V |
| Relay coil resistance | | R_{Rel} | 60 | | | Ω |
| Output current | | I_8 | | | 300 | mA |
| Normal operation | | | | | | |
| Output pulse current | | I_8 | | | 1.5 | A |
| Load dump | | | | | | |
| Internal Z-diode | | V_8 | | 28 | | V |
| Short circuit threshold | | I_8 | 500 | | | mA |

| Parameters | Test Conditions / Pin | Symbol | Min | Typ | Max | Unit |
|--|----------------------------|--------------|-----------|-------------|-----------|------------|
| Oscillator input | | Pin 5 | | | | |
| Oscillator capacitor | Pin 5 | C_2 | | 100 | | nF |
| Oscillator resistor | Pins 5 and 6 | R_8 | | 220 | | k Ω |
| Basic frequency | | f_0 | | 320 | | Hz |
| Lower switching point | | V_5 | | $0.07 V_6$ | | |
| Upper switching point | External 1 k Ω pot. | V_5 | $0.2 V_6$ | | $0.5 V_6$ | |
| Internal discharge resistance | | R_5 | | 2 | | k Ω |
| Protective diode | V_F = forward voltage | V_5 | | $V_S + V_F$ | | V |
| Times | | | | | | |
| External circuitry – see oscillator input (figure 2) | | | | | | |
| Debouncing times: | | | | | | |
| INT input | | t_4 | 50 | | 125 | ms |
| WASH input | | | | | | |
| Pre-wash delay | | t_1 | 260 | | 540 | ms |
| Reverse delay | | $t_{1,R}$ | 50 | | 125 | ms |
| Park | | t_8 | 14 | | 37 | ms |
| Short circuit | | t_7 | 5 | | 12 | ms |
| Switch-on delay (interval mode) | | t_{4D} | 18 | | 31 | ms |
| Relay activation time | | t_5 | 400 | | 625 | ms |
| Interval pause | | t_6 | 2.25 | | 13.75 | s |
| Dry wiping | | | | | | |
| Without park switch feedback | | t_2 | 2.1 | | 3.5 | s |
| With park switch feedback | | | | 3 | | wipes |

U 842 B

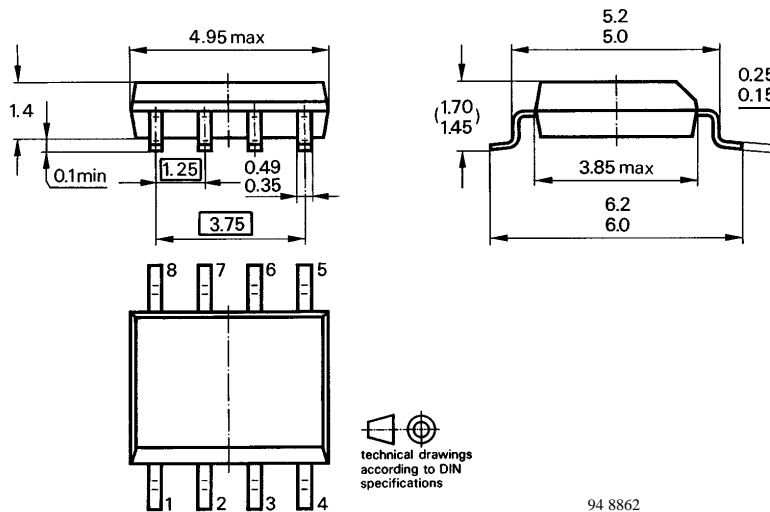
Dimensions in mm

Package: DIP 8



94 8873

Package: SO 8



94 8862

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